

Heritage Impact Assessment

Proposed Sports Centre, Queen's Park Annexe, Chesterfield, Derbyshire

Appendices

Appendix A: Visualisations of the proposal

Appendix B: Visualisation viewpoints

Appendix C: Visualisation methodology

(Recommended print size A3)

on behalf of

Chesterfield Borough Council

November 2013 GLA-138 Appendix A: Visualisations of the proposal



Viewpoint 01: Outline of proposed building



Viewpoint 03: Outline of proposed building

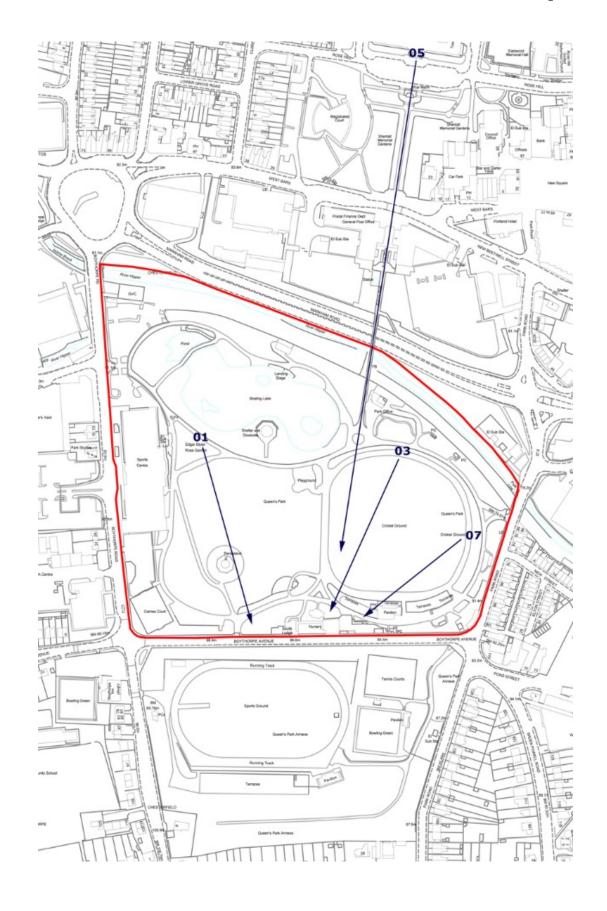


Viewpoint 05: Outline of proposed building



Viewpoint 07: Outline of proposed building

Appendix B: Visualisation viewpoints



Appendix C: Visualisation methodology

AVR METHODOLOGY

Chesterfield. The positions were chosen from information sent over from the design and consultation team.

2D plans, Ordnance Survey Mapping, and a 3D model were provided by Design Cubed Architects, these were used by AVR London In professional architectural photography, having the camera horizontal is desirable in order to prevent any 3-point perspective being to verify the proposal from the selected viewing positions.

Surveying

Control stations were established at each camera position and easily and clearly identifiable static points within the view were identified by the chartered land surveyor on site and marked as an overlay on the photograph from that position.

The survey control stations are resected from the OS base mapping and wherever possible, linked together to form a survey network. This means that survey information is accurate to tolerances quoted by GPS survey methods in plan and commensurate with this in

Horizontal and vertical angle observations from the control stations allow the previously identified points within the view to be surveyed using line of sight surveying and the accurate coordination of these points determined using an intersection program. These points are

The 3D computer model was supplied aligned on the Ordnance Survey coordinate grid system and approved by the architects with then related back to the Ordnance Survey grid and provided in a spreadsheet format.

ground) to identify 3 or 4 features that fall along the horizon line.

Surveying equipment used:

Wild/Leica TC1000 electronic theodolite which has 3" angle measuring accuracy and 3mm + 2ppm distance measuring accuracy. Wild/Leica NAK2 automatic level which a standard deviation of +/- 0.7mm/km

Photography

lens was positioned at a height of 1.60 metres above the ground to simulate average viewing height. Each view was taken with a lens objectively calculated. that gave approximately a 68 degree field of view, either in landscape or portrait format, a standard which has emerged for verified

AVR London were commissioned in November 2013 to produce a number of verified images of the proposal known as Queen's Park, architectural photography. The nature of digital photography means that a record of the time and date of each photograph is embedded within the file; this metadata allows accurate lighting timings to be recreated within the computer model.

> introduced to the image and ensure the verticals within the photographed scene remain parallel. Within architectural photography this is standard practice and more realistically reflects the viewing experience. The camera used by the photographer has the ability to shift the digital capture chip with respect to the centre of the camera lens, allowing for the horizon in the image to be above, below or centrally within the image whilst maintaining the parallel nature of verticals previously mentioned.

> Using the surveyed horizon points as a guide, each photograph is checked and rotated, if necessary, in proprietary digital image manipulation software to ensure that the horizon line on the photograph is level and coincident with the information received from the

Accurate Visual Representation Production Process

levels being cross checked to Ordnan ce Survey heights.

The required horizon line within the image is established using the horizontal collimation of the theodolite (set to 1.60m above the Within the 3D software a virtual camera was set up using the coordinates provided by the surveyor along with the previously identified points within the scene. The virtual camera was verified by matching the contextual surveyed points with matching points within the overlaid photograph. As all the surveyed points, virtual camera and 3D model all relate to the same 3-Dimensional coordinate system then there is only one position, viewing direction and field of view where all these points coincide with the actual photograph from site. The virtual camera is now verified against the site photograph.

> The proprietary 3D modeling software then uses the verified virtual camera and 3D digital model to produce a computer generated render of the proposed building. The proposal was masked where it would be obscured behind built form or vegetation.

Each scene was photographed using a plumb line over a survey pin to accurately position the view location. The centre of the camera

Using the surveyed information and verification process described above, the scale and position of a proposal with a scene can be

Point	Easting	Northing	Level
1	437977.80	370684.83	83.57
2	437967.78	370695.16	93.80
3	437967.60	370696.19	84.23
4	437964.12	370697.48	86.67
5	437958.03	370697.67	83.12
6	437947.71	370695.65	91.05
7	437937.91	370697.23	85.66
8	437932.98	370705.03	82.66
9	437927.06	370706.25	82.67
10	437866.88	370684.46	94.47
11	437899.70	370718.07	83.17
12	437889.73	370726.55	90.72
13	437893.35	370749.02	82.32
14	437893.56	370759.95	82.20
15	437883.63	370756.10	100.05
16	437749.08	370767.05	91.12

